



NAVIGATION TRAINING METHODS FOR LOW-ALTITUDE FLIGHT

Judi Qualy
Dieter W. Jahns
J. D. Gilmour

Boeing Military Airplane Company Seattle, Washington 98124

Daira Paulson
Navy Personnel Research and Development Center

Reviewed by James S. McMichael

Released by James F. Kelly, Jr. Commanding Officer

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II) to low-altitude fixed-wing navigation was developed to	improve visual orientation skills				
of Marine Corps aircrews. The course consisted of a sli	de-tape illustrated lecture and a				
series of dynamic simulation exercises using 70-mm					
advanced aircrew training instructors participated in the the course and served as subject-matter experts. MITAC					
improving low-altitude orientation with specific impro	evements recommended for the				
production model	TO THE				

FOREWORD

This research and development was conducted under contract N00123-79-C-1461 with the Boeing Military Airplane Company in support of exploratory development task area ZF63.521.080 (USMC Manpower and Training Technology) and was sponsored by Headquarters, Marine Corps (Code APW). It is concerned with efforts to apply map interpretation and terrain analysis methods in support of visual geographic orientation training for Navy and Marine Corps aircrews involved in low-altitude operations.

Appreciation is expressed to the aircrews of Marine Aviation Weapons and Tactics Squadron-One (MAWTS-1), Marine Corps Air Station, Yuma, Arizona and Fighter Squadron (FITRON) 124, Naval Air Station, Miramar, San Diego, California for their participation in the feasibility demonstration. Special appreciation is expressed to Major J. D. Wojtasek, MAWTS-1, and LCDR J. Dodge, FITRON 124, for their efforts in coordinating the aircrews and providing operational recommendations to the course.

The contracting officer's technical representative was Orvin A. Larson. The recommendations herein are directed to Headquarters, Marine Corps.

JAMES F. KELLY, JR. Commanding Officer

JAMES J. REGAN Technical Director

SUMMARY

Problem

High-speed, low-altitude flight in fixed-wing aircraft presents unique problems in accurate navigation and orientation. These problems include the extreme dynamic geometry of the landscape and the restricted geographic frame-of-reference not encountered at medium and higher altitudes.

Objective

The objective of this study was to apply map interpretation and terrain analysis methods to the low-altitude geographic orientation problem.

Approach

A map interpretation and terrain analysis course (MITAC-II) was developed to improve visual orientation skills of Marine Corps aircrews through a tape-and-dual-slide lecture format. The lecture was complemented by dynamic low-altitude orientation exercises that allowed participants to practice lessons given in the tape-and-dual-slide lecture. The prototype training course was evaluated by aircrew instructors from the Marine Corps Air Station, Yuma, Arizona and Naval Air Station, Miramar, San Diego, California.

Findings

Participants indicated that MITAC-II was a valuable training tool and that it increased their awareness of topography and contributed significantly to their ability to convert their map into a three-dimensional terrain picture. The content and objectives of the course were compatible with the requirements and past experiences of these qualified aviators. The dynamic exercises were reported to be an effective method of training and the wide-angle screen was extremely effective in achieving realistic visual orientation.

Conclusion

Use of MITAC-II as a training concept and approach to low-altitude orientation is progressive and advantageous. The exercises, using the wide-angle visual system, are effective in integrating the training content with operational tasks.

Recommendations

- 1. Improvements are possible in some areas, including refining lecture graphics, offering a wider diversity of terrain type, emphasizing balance within the lecture modules, and improving performance cues and response measures.
- 2. The event switch that causes the film frame number and plotting mark points to be recorded at each response on the map should be refined for simplified training delivery.
- 3. The event-switch data could be improved by providing participants with additional response-procedure instructions and familiarization.
- 4. The mark point plotting technique used with the corridor exercises could be improved by use of a multiple-choice response set on the map.

- 5. MITAC-II should be evaluated for training effectiveness using aircrew personnel from an operational squadron.
- 6. The illustrated lecture portion of MITAC-II should be evaluated to determine its training effectiveness as a "stand alone" product.
- 7. Alternate visual media configurations should be evaluated to determine the most effective training delivery system.

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INTRODUCTION -

Problem

Geographic orientation in air operations imposes unique and severe problems for the aircrews and systems. The restricted geographic frame of reference and extreme dynamic geometry of the landscape encountered at minimum terrain clearance altitudes in a tactical combat environment, make accurate navigation more difficult than at medium and higher altitudes. The limitations or even absence of traditional navigation aids at low altitudes lead to increased crew workload, and the introduction of small navigation errors can disorient the pilot and lower the probability of successful mission accomplishment. A need exists, therefore, to explore techniques that enable the aircrew to achieve precise low-altitude orientation consistent with current and anticipated mission requirements.

Objective

The objective of this research was to demonstrate the feasibility of using map interpretation and terrain analysis methods to instruct aircrews in low-altitude orientation.

Background

In 1975, the Army Research Institute (ARI) sponsored a project to design and develop a map interpretation and terrain analysis course (MITAC) to improve the ability of Army helicopter pilots to navigate accurately when flying at nap-of-the-earth (NOE) altitudes. MITAC was designed to supplement conventional training by increasing the knowledge of aviators on the many rules and conventions that cartographers follow when constructing maps. The instruction included the basis for the selection and classification of roads, coding criteria for vegetation cover, ground rules for delineating relief and drainage, the conventions used for grouping cultural features under standard symbols, the generalization and displacement practices in cartographic drafting, and many other design practices that must be understood if maps are to be interpreted accurately. To supplement the instruction, MITAC provided practical training through cinematic simulation exercises.

In 1978, the course for Army helicopter pilots was modified by the Navy Personnel Research and Development Center for use by the Marine Corps rotary-wing community.² MITAC has been well received by the aviation community and is now being used to train Army, Navy, and Marine Corps helicopter pilots.

TRAINING COURSE DEVELOPMENT

Weapons and tactics instructors (WTIs) from Marine Aviation Weapons and Tactics Squadron-One (MAWTS-I), Marine Corps Air Station, Yuma, Arizona were interviewed to identify the requirements of aircrews involved in low-altitude operations and the training

¹McGrath, J. J., & Foster, E. A. <u>Development of a system of aircrew training in napof-the-earth navigation</u>. Santa Barbara, CA: Anacapa Sciences, Inc., January 1975.

²NAVPERSRANDCEN memorandum 306:OAL:11p of 13 Apr 1978 to Headquarters, U.S. Marine Corps (Code APW); subj: USMC air navigation training: interim recommendations for

procedures currently used. Data obtained were used as the baseline for developing the low-altitude orientation training program. This program, which is called MITAC-II to distinguish it from the previous rotary-wing course, consists of an illustrated lecture and dynamic exercises. Both are described below.

lilustrated Lecture

The illustrated lecture is presented in a dual-slide and tape format. The lecture is composed of five sections, beginning with a general introduction and followed by information on four topic areas (topography, hydrography, vegetation, and cultural features). It concludes with a series of static orientation exercises. The entire lecture, including the orientation exercises, runs 4-½ hours.

The lecture is illustrated with 350 real-world scenes (35-mm slides), which were selected from the Boeing Film Imagery Library. The scenes, each of which is matched with a slide of its map portrayal, provide visual examples of the various features discussed in the taped lecture narrations.

Dynamic Exercises

Selection of Mission Films

The 70-mm film imagery used for the dynamic exercises was obtained from the Boeing Film Library. A total of 40 mission films are available, which were developed from imagery obtained during programs supporting Joint Task Force Two (JTF-2) and the Combat Air Support Target Acquisition (Project SEEKVAL) test activities. The purpose of the JTF-2 program, which was a joint-service test and evaluation effort conducted by the Joint Chiefs of Staff between 1965 and 1968, was to evaluate all phases of the low-altitude mission through a combination of field tests, simulation, and analysis/modeling techniques. Simulation imagery developed under this program included filmed routes at 200-, 400-, and 600-foot altitudes, at 1/4- and 1/2-mile offsets in addition to centerline, and filming conditions that allowed a dynamic range of projection playback speeds from 180 to 800 knots.

The SEEKVAL test program, conducted during 1972-74, was administered by the Air Force Test and Evaluation Command (AFTEC). Its purpose was to evaluate target acquisition system concepts using direct or aided vision. For purposes of the current demonstration program, the JTF-2 and SEEKVAL imagery adequately portrayed the flight profile, field-of-view, image quality, color, and dynamic geometry conditions needed to demonstrate feasibility of the MITAC-II program.

Prior to selecting mission films for the dynamic exercises, nominal flight tracks were plotted for each to determine the type of terrain and cultural features contained in the film imagery. Using the course tracks as a guideline, 10 mission films were selected based on the following criteria:

- 1. Flight altitudes could not exceed 500 feet above ground level (AGL).
- 2. Filmed flights had to cover a variety of terrain relief while at the same time avoiding flying parallel to roads, transmission lines, etc., over extended distances.
- 3. The available projection speeds had to be capable of simulating airspeeds from 240 knots to 500 knots.

4. Films had to be of good quality, in terms of brightness, resolution, and image stability.

After the selection was made, two copies of each complete film were printed, spliced, and assembled into mission films. In some cases, not all of the original film was used because of excessive length, lack of significant terrain features, or excessive cultural features. Nominal course plots for each mission film served as a baseline for a more detailed ground-track plotting. Selected films, in the sequence used, are listed in Appendix A.

Videotapes of each mission film were made at 180 knots and at 240 knots. The 240-knot videotapes were used to prepare and time the feedback debrief narrations to be used in the simulator following each dynamic exercise (performance run). During the debrief simulation, the audio channel from these tapes was used to provide a feedback narration played in synchronization with the film. The 180-knot videotapes were used in preparing the debrief narration and as an off-line or out-of-simulator debrief where the participants could stop the tape at any time to examine a feature more closely.

Designation of Mark Points and Turn Points

Mark points (selected features for participant response) and turn points (heading changes) were designated for all flights. Mark point selections were based on relevance to training objectives covered in the illustrated lecture and the visual significance of the mapped features. The number of mark points per mission ranged from 4 to 15, depending on mission length. A brief description of the mark points used in each film is included in Appendix B.

After the mark points had been selected, they were catalogued by frame number relative to the beginning of the mission film. This involved several steps using a 70-mm projector, digital frame counter with memory, and a light table with a frame counter. The frame number for a mark point was selected when the feature was just off the bottom of the frame, representing the nadir or abeam position in the simulator.

Turn points were visually identified while reviewing each film on the wide-screen visual system. They were catalogued using a digital frame counter to record the entering and exiting frame numbers. These frame numbers were used to drive the magnetic heading display. Mission sequence and projection speed/airspeed were agreed upon and detailed ground tracks for all films were plotted.

All mission data were assembled into a notebook by mission film. An example of the format and data is included in Appendix A. Simulation instructions and the response procedures for the simulator portion were developed along with the sequence of events for the feasibility demonstration period.

Preparation of Software and Instructional Materials

When the preliminary design was complete, preparation of software and instructional materials commenced. Programming of mark point and turn point frame numbers, projector speed/airspeed control, instrumentation signals, control signals, and throttle control was completed. Narrations for the preflight briefings and simulation debriefings were written and taped.

Preflight briefing materials used by participants to prepare for each mission included Joint Operations Graphic (JOG) air charts and taped narrations discussing topography,

hydrography, vegetation, and cultural features of the flight operations area. The JOG-Air maps (1:250,000 scale) were prepared as mosaics covering the area of interest. The flight track (first three maps) or corridor (last six maps) was marked on the map, as were mark points for selected missions. The maps were laminated with mylar to permit repeated use and to facilitate easy clean-up.

The debriefing materials also included taped narrations and annotated maps. The narrations served to reinforce the orientation principles from the lecture and to provide immediate feedback on orientation performance along the flight track. The maps contained the actual flight track and mark points as well as additional annotated orientation features that were reviewed in the taped narrations.

Simulation Facility

The dynamic exercises were given in the combat aircraft mission simulator at the Boeing Space Center, Kent, Washington. The simulator is an integrated avionics simulation facility composed of several hardware elements with attendant software modules. Various elements and modules are combined, based on mission requirements, to provide the needed crew/cockpit interfaces. The elements used in the course consisted of a multimission simulator lab (MMS) and the Varian 75 computers located in the visual flight simulation lab (VFS) (see Figure 1).

The MMS houses the crew stations, visual display system, and the test instrumentation for conduct of visual flight rules (VFR) and instrument flight rules (IFR) part-task or full-mission simulations. The visual display system, using a wide-angle screen, projects high-resolution cinematography. The wide-angle display encompasses 160 degrees laterally by 60 degrees vertically. The MMS cockpit, which is situated in the center of a 15-foot radius spherical-section screen, is representative of a mid-1980 fighter/attack aircraft and is in a one-place configuration. Cockpit instrumentation was checked and determined to be adequate for the MITAC-II feasibility demonstration.

In the VFR operating mode, imagery from a 70-mm projector recreates the dynamic geometry that would be experienced during actual flight. An arc lamp provides a screen illumination that is nearly the color of daylight and has an open-gate brightness of approximately 20 ft. Lamberts.

A limited number of instruments were activated for the present simulation. These included the airspeed indicator, the altimeter, the radio magnetic indicator, and a digital clock. Control of simulation action was provided by an event switch; and control of airspeed/projector speed for selected exercise films, by a throttle (see Figure 2).

Overall simulation control and data recording were accomplished using the Varian 75 computers, which drove the cockpit instruments and provided the aircraft flight characteristics. The computers also controlled the projector speed/airspeed and cued the tone generator to transmit response stimuli to the participant.

Airspeed was controlled by the computers for seven of the runs. During the two final runs, the participant controlled the airspeed using the throttle. Limits on airspeed in the manual-control mode (500 kts) were dictated by the safe operating limits of the projector and task fidelity.

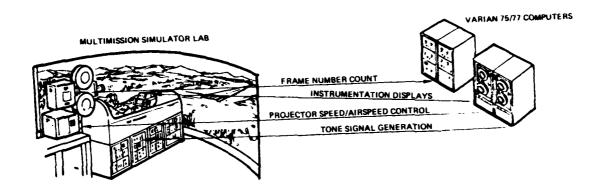


Figure 1. Simulation configuration.

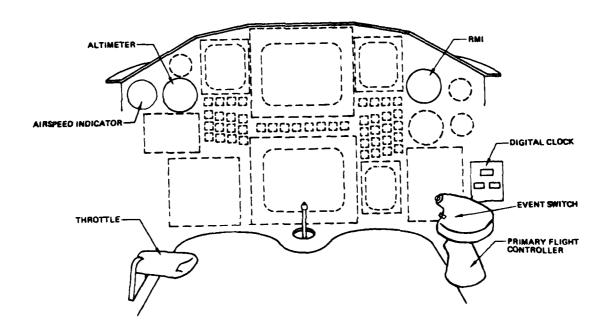


Figure 2. Cockpit configuration for MITAC-II demonstration.

FEASIBILITY DEMONSTRATION

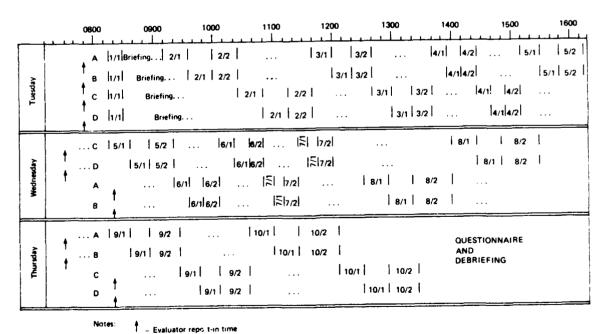
Participants

Fifteen subject matter experts (SMEs) participated in the feasibility demonstration of MITAC-II. Eleven of the participants were WTIs from MAWTS-1, and the other four were advanced crew-training instructors from Fighter Squadron (FITRON) 124, Naval Air Station (NAS), Miramar, San Diego, California. Six of the participants were pilots, six were radar intercept officers, one was an aerial observer, and two were bombardier/navigators. They represented the F-4, RF-4, A-4, A-6, OV-10, and F-14 aircraft communities.

Procedures

Participants reported to the briefing room at the Boeing Space Center in groups of four. After a short introduction, they completed a demographics questionnaire and the first portion of the illustrated lecture questionnaire (Appendices C and D). The 4½-hour illustrated lecture was then presented. As each module of the lecture was completed, it was critiqued by the participants and test personnel. All comments were recorded. Following the lecture, the participants completed the remainder of the illustrated lecture questionnaire.

Participants, in groups of two, were then briefed on the cockpit and simulator, and received instruction on the procedures to be used in the dynamic mission exercises. For the first nine missions, one pair would "fly" and the other pair would brief. These pairs exchanged flying and briefing roles for the subsequent nine missions. As shown in Figure 3, participants flew an initial or performance run individually, and a second or debriefing run together. Each participant, therefore, saw each mission film twice.



| | Evaluator reps t-in time |/| = Numerator is Sequence Number; Denominator is Run Number

Figure 3. Simulation overall run sequence.

A standardized briefing procedure was used for all mission films. Participants spent 5 to 15 minutes studying the track and preparing a flight plan. They then listened to the preflight briefing narration tape for the particular mission. Upon completion of the preflight briefing tape, the participants were given additional time to review their flight plan and to mark changes on the laminated maps using water-soluable marking pens. The briefing time lasted 20 to 40 minutes depending on the length of the mission film. Additional information given the participants included (1) entry-point descriptions, (2) estimated time of arrival (ETA), based on zero time for appearance of first image frame, (3) total length of mission in nautical miles and total estimated time enroute (ETE), (4) airspeed, automatic or manual throttle, (5) nominal altitude above ground level (AGL), and (6) initial heading.

The task and response procedures for performance runs differed, depending on the mission sequence number. As shown in Table A-2, missions 2, 3, and 4 were "along-track" exercises, in which the ground track and mark points were preplotted on the map. When the participant determined he was abeam the mark point, he pressed the event switch on the side-arm controller. The computer then recorded the frame number.

Missions 5, 6, and 7 were "limited-corridor" exercises, using a 4-statute-mile-wide corridor plotted on the briefing maps. Missions 8, 9, and 10 were "corridor" exercises, using 10-statute-mile-wide corridors. The response procedures for sequences 5 through 10 were the same. Approximately 5 seconds before reaching a mark or response point, the participant received a "Ready" tone over his headset. This tone alerted him to prepare to mark his current position on the map. When he heard the next tone, the "Mark" signal, he marked what he determined to be his ground position on the map.

When both "flying" participants had completed their performance runs, they were provided a debrief map that contained the original track or corridor, plus other annotated map features. In the case of the corridor exercises, the ground track and mark points were also plotted on the debrief map. After reviewing the debrief maps, the two participants watched the mission film a second time at 240 knots and listened to the debrief narration played along with the film. When all four participants had completed all of the exercises, they completed the dynamic exercise (simulator) questionnaire.

Evaluation Techniques

The questionnaires served as the primary evaluation measure. Three questionnaires were used: (1) the participant demographics questionnaire, (2) the evaluative questionnaire No. 1—illustrated lecture, and (3) the evaluative questionnaire No. 2—dynamic (simulator) exercises. (Responses to the questionnaires are summarized in Appendices C, D, and \vec{E} .)

An additional evaluation measure was mark point acquisition error. On mission runs 2, 3, and 4, the event switch was depressed when the participant determined he was over or abeam the preplotted mark point. The computer recorded the frame number and computed a delta from the catalogue frame number for that mark point. The delta was later converted into ground feet (see Appendix B). A correct response, or accuracy criterion, was considered to be within \pm 0.5 nm (\pm 3040 ft) of the catalogued mark point location.

In missions 5 through 10, the evaluative technique compared the participant's mark points from his performance map with the correct responses plotted on the debriefing map. Also, the errors were orally debriefed by a NAVPERSRANDCEN geographer to

provide better understanding of perceptional or interpretive problems related to the training objectives.

In the "along-track" exercises (see Appendix B for the objective performance measures), the route and mark points were preplotted on the map. When the participant was over or abeam the mark point, he indicated recognition by activating the response switch that recorded the film frame number. The frame number deltas were converted into ground feet, where frame number delta is defined as the difference between the film frame number corresponding to the map-plotted mark point and the film frame number at which the participant responded. Means and standard deviations were then calculated and plotted. An accuracy criterion of ± 0.5 nm was used. If a participant's response was greater, it was considered a miss and was not included in later calculations. This (as well as a "no" response), resulted in a different number of responses (n) between mark points. The mean distance from the catalogued mark point is plotted by the "X" with one standard deviation represented by the bar. The results were also correlated with response time, which was a function of ground speed. The statistical data indicate that those features having a defined edge or boundary have a smaller standard deviation than those lacking a well defined edge. The majority of responses were made within 2 seconds of the desired response point.

The results from the "limited corridor" and "corridor" exercises were not recorded in this same manner. During the corridor exercises, a tone was sounded that required the participant to mark his aircraft position on the map. These response marks were orally debriefed. No quantitative data were collected on the accuracy of the response.

The primary emphasis in the prototype course was on performance feedback rather than performance evaluation. As such, it relied heavily on knowledge of results and immediate feedback rather than on measures readily amenable to automated data collection.

RESULTS AND DISCUSSION

Participants indicated that MITAC-II was a valuable training tool. (Responses provided in questionnaire summaries and an example of performance data are included in Appendices B, C, D, and E.)

Respondents to the illustrated lecture questionnaire reported that, while the training course would not change their methods of flight planning and visual search, it definitely would make them more aware of the usefulness of topography and better able to convert their map into a three-dimensional terrain picture. Significantly, the content and objectives of the course were fully compatible with the requirements and past experiences of these highly qualified aviators. With only minor exceptions, comments indicated that the presentation of information in the individual lecture modules was acceptable. The participants also suggested that (1) an additional lecture module should be developed to integrate and summarize the information presented in the illustrated lecture, and (2) feature combinations and regional variations should be further emphasized. (It should be noted that the lecture itself was never intended to stand alone but, rather, to be used in concert with the dynamic practice and drill exercises to achieve the desired integration.)

Responses to the simulation exercises questionnaire were also positive. The SMEs felt the performance-run and debrief-run combination was an effective method and that the wide-angle visual system was extremely useful for realistic visual orientation. They suggested that (1) the debrief run, on all missions except those at 240 knots, be shown at

the same speed as the performance run, and (2) the coincidence of the "ready" and "mark" tones with the selected response points should be timed more accurately on some features.

The SMEs also commented that, as a map interpretation and terrain analysis course, the system met the objective and, as such, strongly supports navigation techniques for low-altitude operations. However, the distinction between orientation training and navigation training must be clearly made. They also indicated that a wider variety of terrain types should be included in a production course.

New imagery could be procured for the course either by obtaining additional existing Department of Defense (DoD) imagery or by filming new routes, which would allow greater variation in terrain types. Variations might include seasonal changes, shadow/sun problems, and unique mission scenarios such as coastal penetration. New film imagery would offer maximum training benefits, ensuring that film frame rates could be selected for a range of playback speeds to reduce any possible flicker effects. Also, mission profiles, including length, altitude, number, and rate of turns, could be optimized. Films could be tailored to specific training objectives and the illustrated lectures planned around them. Such films, over an extended period, would be cost beneficial.

Changes in equipment and procedures to improve the course were also discussed with participants. For example, it was suggested that screen size could be reduced from the present 15-foot radius spherical-section to a minimum of a 10-foot radius, thus reducing the cost while still maintaining the wrap-around effect. Although other film formats were discussed, it was noted that those having the wrap-around effect and the same or better image quality are not currently available. The primary parameters to consider in film choice are overall film area and aspect ratio. Also, to maintain the 160-degree visual scene, a film aspect ratio in excess of 2:1 is necessary. This constraint applies when linear optical systems, rather than the nonlinear cinemascope, are used. The 70-mm film has approximately this ratio. A double-frame 35-mm format is a possibility but is costly and difficult to handle.

During the feasibility demonstration, the Varian 75 computers controlled the projector speed/airspeed, drove the simulator instrumentation, cued the tone generator, and recorded participants' responses. The participants agreed that full instrumentation was not needed since the "flight" is a "canned" mission. However, the remaining necessary instrumentation and cueing could easily be handled by today's microprocessors.

Because the feasibility demonstration was conducted at a research facility, a large number of personnel was required. In a production course, the illustrated lecture would be tutorial, eliminating the need for support personnel. Once the mission films are assembled and the microprocessor programmed, the dynamic exercises would require only one projector technician.

CONCLUSIONS

Responses indicated that the MITAC-II concept and approach to low-altitude visual orientation training is progressive and advantageous. The format and content of the illustrated lecture were considered informative and were approved by the SMEs. The simulation, using the wide-angle visual system, was effective in providing the necessary environment to integrate the training content with operational tasks. The two components, acquisition of new skills in map interpretation and terrain analysis from the

illustrated lecture and use of the simulator to exercise the new skills in real-time, complemented each other well.

RECOMMENDATIONS

- 1. Improvements are possible in some areas, including refining lecture graphics, offering a wider diversity of terrain type, emphasizing balance within the lecture modules, and improving performance cues and response measures.
- 2. The event switch that causes the film frame number and plotting mark points to be recorded at each response on the map should be refined for simplified training delivery.
- 3. The event-switch data could be improved by providing participants with additional response-procedure instructions and familiarization.
- 4. The mark point plotting technique used with the corridor exercises could be improved by use of a multiple-choice response set on the map.
- 5. MITAC-II should be evaluated for training effectiveness using aircrew personnel from an operational squadron.
- 6. The illustrated lecture portion of MITAC-II should be evaluated to determine its training effectiveness as a "stand alone" product.
- 7. Alternate visual media configurations should be evaluated to determine the most effective training delivery system.

APPENDIX A
SIMULATION SUPPORT DATA

LOW-ALTITUDE NAVIGATION SIMULATION

Mission: Ft. Lewis Track A Total No. Frames: 9,671 Sequence No.: 7 Ground feet/frame: 21.3 Total Distance: 33.5 nm Ground Speed: 360 Kts. = 28.5 frames/second (Performance Run) 240 Kts. = 19.0 frames/second (Debriefing Run) 180 Kts. = 14.25 frames/second (Off-line Debrief) Performance Run (1): Page 1 of 3 Frame No. Event Action 00000 Project Start Start computer and projector (28.5 fr/s) A/S, Altimeter, RMI on Initial Heading: 550T (340M) Lat: 460 46' 00"N Long: 1230 04' 00"W Altimeter: 500 ft Airspeed: 360 Kts (1) 878 "Ready" tones Tone generator signals (2) 906 (1st mark point) two beeps 1020 "Mark" tone Tone generator signals 1st mark point one beep (1) 2983 "Ready" tones Tone generator signals (2) 3011 two beeps (2nd mark point) 3125 "Mark" tone Tone generator signals 2nd mark point one beep (1) 6445 "Ready" tones Tone generator signals (2) 6473 (3rd mark point) two beeps 6587 "Mark" tone Tone generator signals 3rd mark point one beep (1) 9110 "Ready" tone Tone generator signals (2) 9138 (4th mark point) two beeps 9252 "Mark" tone Tone generator signals 4th mark point one beep 9671 End of film/run Projector/Computer off

Figure A-1. Simulation Data Notebook Example

Lat: 47º 04' 30"N Long: 122º 25' 00"W

SEEK										
SEEK										
	VAL TR	ACK "A						ļ		
SEOU	ENCE #	7 TAKE-OF	FTIME	PERFO	RMANCE	RUN TOTAL E	TE	TOTAL A	AT FUEL	
			•	33.6			5			
BTUOR	IDENT	IDENT	MAG	DISTANCE	GROUND	ETE	ETA	LEG	ACTUAL	
	FREQ	FREQ	CRS	REMAIN	SPEED	REMAIN	ATA	REMAIN	REMAIN	
S				0		0	0			
			034	33.6	360	5+36				
1			1	3.6		0+33	0+33			
R			034	30.0	360	5+00				
2]	7.4		1+14	1+47			
			034	22.6	360	3+46		<u> </u>		
3			1	12.1		2+01	3+48		Ì	
			034	10.5	360	1+45	<u> </u>			
4		Ĺ		9.3	`	1+33	5+21			
			034	1.2	360	0+12			<u> </u>	
E] '	1.2		0+12	5+36			
			034	0	360	0				
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AF FORM 70 REPLACES AF FORM 21A, JAN 63, WHICH WILL MAY 66 TO BE USED UNTIL STOCK IS EXHAUSTED.

Figure A-1. (Continued)

Event Summary

Mission: Ft. Lewis Track A

Page 3 of 3 Sequence No: 7

470 04' 30"N Lat: 460 46' 00"N Long: 1230 04' 00"W Start Lat: End Lat:

Long: 1220 25' 00"W

Headings (I(H)) 210 Variance

<u>I(H)</u> Frame No. <u>I(H)</u> Frame No.

0000 55T (34M)

NO TURNS

Checkpoint NADIR/ABEAM

Frame No. Ckpt. ID Frame No. Ckpt. ID 1. 1020 Bend in I-5 & RR 2. 3125 Tenino Rd - RR River - Powerhouse 3. 6587 Rd - RR crossover 4. 9252

Figure A-1. (Concluded)

Table A-1 Mission Characteristics of MITAC-II Simulation Films

COMMENTS	Broad plains mixed with small forested areas. Flat terrain with evidence of military activity. Many cultural features. Ends over Puget Sound.	Initial Latitude: 46057'15"N Initial Longitude: 122015'00"NW Final Latitude: 47006'00"N Final Longitude: 122040'45"W	Rolling terrain. Sparsely populated. Ridge lines run east-west. Forested area rather than agricultural.	Initial Latitude: 36016'00"N Initial Longitude: 92013'15"W Final Latitude: 35023'30"N Final Longitude: 93024'00"W	Heavy forestation and sparse population. Several rivers. Gently rolling terrain with up to 800 ft elevation differences. Several flat turns in flight.	Initial Latitude: 34040'00"N Initial Longitude: 96002'00"W Final Latitude: 34019'30"N Final Longitude: 95003'30"W
GROUND COVERAGE NM/FILM FOOTAGE	19.5/490		78.0/1367		48.2/1220	
SPEED RANGE, KNOTS	204 - 362		288 - 512		198 - 352	
ALTITUDE, FEET	200		300		300	
LOCATION	Ft. Lewis Army Reservation, Washington		Arkansas- Oklahoma Border Area		Arkansas- Oklahoma Border Area	
FILM IDENTIFICATION	SEEKVAL D		N-NAV-300 Part I		N-P-300 Part II	
SEQUENCE	1	-	2		m	

Table A-1 (continued)

COMMENTS	Semi-arid landscape. Sharply rolling terrain with intermittent plateaus. Two towns.	Initial Latitude: 35043'15"N Initial Longitude: 120043'30"W Final Latitude: 36010'30"M Final Longitude: 121008'30"W	Rolling terrain. Sparsely popu- lated. Ridge lines run east-west. Forested area rather than agricul- tural.	Initial Latitude: 35023'45"N Initial Longitude: 93023'30"W Final Latitude: 34020'30"N Final Longitude: 94039'30"W	Heavy forestation and sparse population. Several rivers. Gently rolling terrain with up to 800 ft elevation differences. Several flat turns in flight.
	Semi-a rollin platea	Initia Initia Final	Rollin lated. Forest tural.	Initia Initia Final	Heavy lation rollin elevat
GROUND COVERAGE NM/FILM FOOTAGE	46.8/996		86.7/1519		48.5/1225
SPEED RANGE, KNOTS	360 - 420		288 - 512		198 - 352
ALTITUDE, FEET			300		300
LOCATION	Hunter-Liggett Military Reservation, California		Arkansas- Oklahoma Border Area		Arkansas- Oklahoma Border Area
FILM IDENTIFICATION	Hunter-Liggett Demonstration		N-NAV-300 Part Il		N-P-300 Part I
SEQUENCE	₹		vo		w

34023'30"N 94057'45"W 34048'30"N 95056'30"W

Initial Latitude: Initial Longitude: Final Latitude: Final Longitude:

Table A-1 (continued)

COMMENTS	Flat terrain with evidence of military activity. Mt. Rainier prominent throughout most of flight. Broad plains mixed with small forested areas.	Initial Latitude: 46046'00"N Initial Longitude: 123004'00"W Final Latitude: 47004'30"N Final Longitude: 122025'00"W	Flight track perpendicular to major ridge lines. 1500 ft elevation difference. More cultural development than some others. One lag of flight parallels ridge lines.	Inital Latitude: 34°00'00"N Initial Longitude: 95°38'30"W Final Latitude: 34°22'45"N Final Longitude: 94°28'00"W	Broad plains dominated by agriculture and forestry. Flight track crosses numerous roads. Long, straight legs. Terrain very flat.	Initial Latitude: 32029'30"N Initial Longitude: 93008'30"W Final Latitude: 34014'00"N Final Longitude: 93045'30"W
GROUND COVERAGE NM/FILM FOOTAGE	33.5/736		145.6/2639		112.0/2639	
SPEED RANGE, KNOTS	204 - 362		288 - 512		288 - 512	
ALTITUDE, FEET	200		200		400	
LOCATION	Ft. Lewis Army Reservation, Washington		Louisiana- Arkansas- Oklahoma		Louísiana- Arkansas- Oklahoma	
FILM IDENTIFICATION	SEEKVAL A		M-TA-200		W-NAV-400	
SEQUENCE	~		œ		on .	

Table A-1 (concluded)

COMMENTS	Flight track perpendicular to ridge lines. 1200 ft elevation difference. Less cultural development than W-TA. Flight ends across large lake.	Initial Latitude: 34001'15"N Initial Longitude: 93018'00"W Final Latitude: 34034'30"N Final Longitude: 93008'15"W
GROUND COVERAGE NM/FILM FOOTAGE	148.9/2659	
SPEED RANGE, KNOTS	288 - 512	
ALTITUDE, FEET	500	
LOCATION	Louisiana- Arkansas- Oklahoma	
FILM IDENTIFICATION	E-TA-200	
EQUENCE NUMBER	10	

Table A-2 MITAC-II Simulation Exercise Conditions

MAP FORMAT	Combination	Along-Track	Along-Track	Along-Track	4sm-wide Corridor	4sm-wide Corridor
THROTTLE	AUTO	AUTO	AUTO	AUTO	AUTO	AUTO
ALTITUDE FEET	200	300	300	500	300	300
ED (KTS) Debrief	•	240	240	240	240	240
PLAYBACK SPEED (KTS) PERFORMANCE DEBRIE	240 - 360	240	240	360	360	360
PURPOSE EMPHASIS	Integration of training methods; simulation familiarization	Application of terrain analysis module in illustrated lecture	Increased difficulty; less well defined topographical features	Cultural; physical features, semi-arid terrain; increased airspeed	Skills exercise; change to corridor	Force use of more distant terrain, etc. features
LOCATION	Ft. Lewis Army Reservation, Washington	Arkansas- Oklahoma Border Area	Arkansas- Oklahoma Border Area	Hunter-Liggett Military Reservation, California	Arkansas- Oklahoma Border Area	Arkansas- Oklahoma Border Area
FILM IDENTIFICATION	SEEKVAL D	N-NAV-300 Part I	N-P-300 Part II	Hunter-Liggett Demonstration	N-NAV-300 Part II	N-P-300 Part I
SEQUENCE NUMBER		8	m	4	vo	vo

Table A-2 (concluded)

MAP FORMAT	4sm=w1de Corridor	10sm-wide Corridor	10sm-wide Corridor	10sm-wide corridor
ALTITUDE THROTTLE FEET CONTROL	AUTO	AUTO	MANUAL	MANUAL
ALTITUDE FEET	200	0 2 0	400	500
D (KTS) Debrief	240	240	. 240	. 240
PLAYBACK SPEED (KTS) PERFORMANCE DEBRIEF	360	480	480 (450 - 500)	480 (450 - 500)
PURPOSE EMPHASIS	Vegetation, hydrography, and cultural features; large contour interval	Integration of features; increased airspeed; increased corridor width	Incapration of terrain/ cultural/time/distance	Final integration and review exercise of all training
LOCATION	Ft. Lewis Army Reservation Washington	Louisiana- Arkansas- Oklab∵a	Louisiana- Arkansas- Oklahoma	Louisiana- Arkansas- Oklahoma
FILM IDENTIFICATION	SEEKVAL A	W-TA-200	W-NAV-400	E-TA-200
SEQUENCE NUMBER	4	ω	6	10

APPENDIX B MARK POINT INFORMATION AND ALONG-TRACK EXERCISES RESULTS

This Appendix contains all the mark point descriptions and the results from the Along-Track exercises.

The beginning of the Appendix provides all the information related to the Along-Track exercises. The Tables provide the data of all the participants by mark point. The data are ground-feet deviations from the prebriefed mark point locations. Positive distances indicate late responses by the participants; negative distances indicate early or anticipatory responses. Deviation data were computer-recorded, based on event switch activations by the evaluators. Following each Table is a graphical representation of the results.

The second part of the Appendix provides a listing of the mark points used in the corridor exercises and the approximate distance in nautical miles between them. Designations of these mark points by the participants were made by manually marking the briefing maps upon hearing "mark" signals over the headset. Deviation data as a check for the geographic orientation of the participants were manually recorded by NPRDC personnel during debriefing prior to cleaning the laminated maps for reuse.

Table B-1

Mark Point Variation -- N-NAV-300 Part I

		Deviation Distance	-		- 854	-1282	- 187	160	88	*	267	3578	1095	- 721	-1388	2590	- 667	12	- 178	1273
		Mark Point	ន		λl	8 g	Æ	əu	łd	1	0	47	.10	u	١١	łH	}			
		Deviation Distance	*	- 748	561	- 721	2109	15059	-6862	*	-2456	204	16687	1201	- 881	-4005	-1095	σ	74	1392
AGL		Mark Point	60				u	ł 6	ļu	no	W	Æυ	0 [იე						
300 rt A	feet.	Deviation Distance	587	-1735	- 214	133	53	294	-4646	*	- 454	- 614	8464	- 160	-3898	- 320	-1095	11	- 427	584
	of	Mark Point						_					11							
Altıtude:	in units	Deviation Distance	214	374	540	133	. 240	107	400	*	614	. 187	. 240	- 267	641	. 347	133	14	. 162	305
⋖	distance	Mark Soint	0		•	•	•	19	MQ	1	j n	0)	,	די	•	•	•		•	
v,		Deviation Distance	1068	1175	-2376	- 214	8	-3351	-2483	*	000	- 988	- 347	-5180	-1201	- 854	-2857	12	- 952	1165
240 kts	Deviation	Mark 3αiο9															LIH			
speed:		Deviation Distance	1816	694	- 934	8	-1495	-2216	-2670	*	*	-3711	-2163	587	- 908	-1629	8	12	- 730	1383
አ ን	briefing map.	Mark Point	95	s	δu	ļ	dς	; 3	16	e)	1 4	o	ų:	ını	os	ı	LłH			
	on brie	Deviation Stance	1201	-2083	- 961	- 133	- 854	748	- 801	*	9318	-2697	-1922	- 107	- 881	267	427	13	- 665	1114
Part		Mark Point	홍			ę	?ua	s.	16)	١.	10	1	S e	ə	9 K	əd				
N-NAV-300 Part	preplotted	Deviation Distance	8	- 294	- 107	- 534	374	- 107	5927	*	- 267	- 320	-3658	8	- 294	187	534	12	- 29	315
	point	Mark Point	8					75	PΛį	Я	0	[E	7 7	ng						
Mission:	Mark	Deviation Distance	8	614	-5500	267	203	721		*	294	374	3578	427	- 641	267	203		267	373
Σ		Mark Intoq	8		(3)	uə	33	łm	19	31	11)		19/	1 1 9	1 (1	sîîu	8		
		Deviation Distance	-1682	-2323	-2189	-1789	-2269	-2430	-2323	*	-2189	-2296	-2109	-1949	-3044	-2056	-2136	13	-2134	219
		Mark Point	10			19	MO	1	u j	P :	uı	ηQ	d S	sde	ļį	15				
		Evaluator TadmuM	-	7	m	4	ഹ	ဖ	7	œ	σ	10	Ξ	12	13	14	12		: ×	н

Data lost or no event switch response made by evaluator.

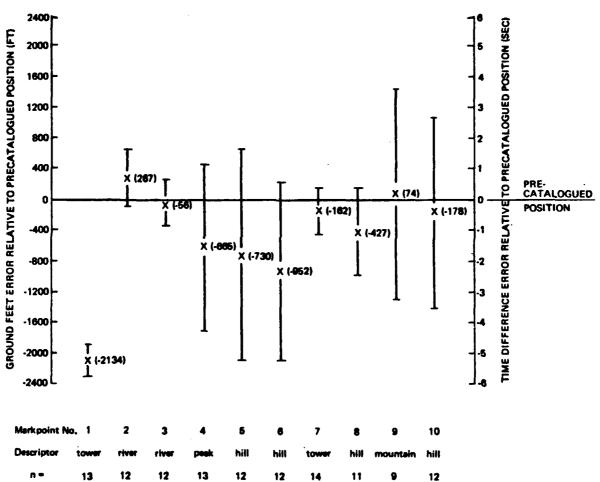


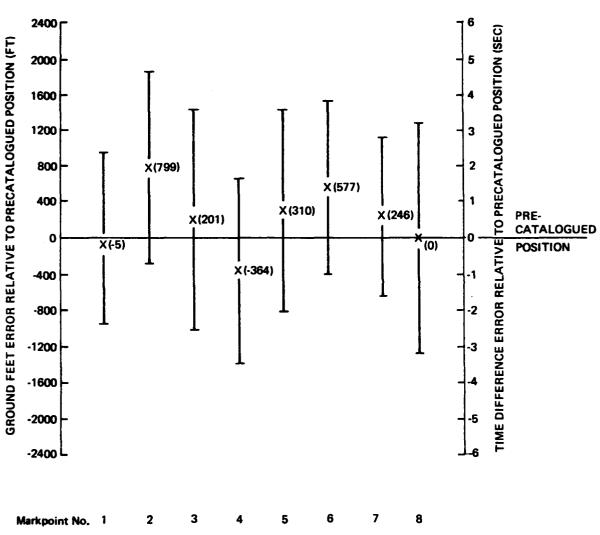
Figure B-1. Summary of Mark Point Data -- N-NAV-300, Part I

Table B-2

Mark Point Variation -- N-P-300 Part II

		Deviation S Distance	7392 8750 * - 7344	370 - 740	- 2349 - 1961 9934	314 314 -10304	1307							
		Hark Juloq	besk g	petore	∌gb∮⊤ bn	2600								
		Deviation Distance	- 333 370 3219 - 370	6438 4403 13301	- 74 3219 4736 3219	851 5624 1961	7 246 913							
Altitude: 300 ft AGL	feet.	- Mark Intoq	04	ands b	26 cou									
	distance in units of	distance in units of	Deviation Distance	1517 74 8269 - 1831	14134 7955 7215	1128 1054 7037 1054	962 8639 925	9 578 985						
			Mark Point	S 92.	iuoo 10	to right	Ridge							
			Deviation Distance	- 148 333 2238 - 9527	3163 425 - 1443	- 777 - 388 - 166 388	92 2627 351	12 310 1132						
240 kts	Deviation	Mark Point	02	ibbss 10	ge left	KIQi								
Speed: 2	Mark point preplotted on briefing map. D	ark point preplotted on briefing map.	briefing map.						Deviation Distance	- 1276 - 74 - 277 - 9694	- 1313 - 814 - 814	- 2072 - 74 - 1776 - 1776	- 203 - 129 1165	13 - 364 1058
Š				Mark Mark	8	. Kidge	Ted nuG							
Mission: N-P-300 Part II				Deviation Distance	- 980 2183 943 - 3885	* - 851 4902 *	314 - 425 - 647 11840	10822 - 832 2109	202 202 1265					
			Mark Point	03 3	bbas an	oled wer	a							
			Deviation Distance	1073 1942 814 -12617	* 444 1813 - 37	- 573 851 - 740	2923 7696 1276	12 799 1097						
			Mark Point	05	taght m	oni wanO								
	٠	Deviation Distance	592 832 - 1073 10933	+ - 962 1480	9993	11914 11914 1054	11 5							
		Mark Point	S puo	d ased e	egbtad bo	Secon								
		Иишрег	4004	5000	900-	7 W 4 W	<u> </u>							

* Data lost or no event switch response made by evaluator.



Markpoint N	lo. 1	2	3	4	5	6	7	8
Descriptor	ridge	draw	draw	ridge	ridge	ridge	spur	ridge
0 =	11	12	۵	13	12	9	7	7

Figure B-2. Summary of Mark Point Data -- N-P-300, Part II

Table B-3

Mark Point Variation -- Hunter-Liggett

Altitude: 200 ft AGL

Speed: 360 kts

Mission: Hunter-Liggett

	Deviation Distance	- 176 - 3014	- 2156 - 682	- 66 814	- 2134 7458	- 396 - 1386	- 484	- 638	- 264 -	14 - 781 1033
	Mark Potot	00	uo£u	18J 9	afq	38 4	Dra			
	Deviation Distance	- 1364 - 2508	88 88	- 484 1342	6864 11902	 89	- 1364	1210	- 1012 - 154	13 - 484 1037
of feet	Mark Point -	8.	reek	uoj	,55 Ji	1 38	Биј	.1 * 3	LO	
Deviation distance in units of feet	Deviation Distance	- 2090	- 66 - 1518	* 88	- 5456	- 6468 - 704	- 2398	905 -	- 770 - 2684	11 - 1250 940
distance	Mark Julo9	90		UM	og p	- 2018 (J	υΩ			
Jeviation	Deviation Distance	- 1100	- 1628	- 3190 10120	- 506	352 8118	8140	188	- 4598 462	. 390 748
map.	Mark Point	8		₽ ¢	əag	uol	იი			
n briefing	Deviation Distance	- 1936	- 1232	396	- 2156	- 550 946	- 726	- 484	- 374 - 1144	14 - 839 626
preplotted on	Mark Point	83	SS	ed-pt	504	Nou) pe	LSH	l	
nt prep)evfation)istance	374	45	396 1056	- 660	418	- 572	- 198 - 198	- 220	15 - 9 494
Mark point	4ark oofnt		P	เทรน	beu Į	eek	י כג	2 1 4-	t &H	
	Deviation Distance	- 968	588	282	638	* 1	374	8 8 9 • •	- 352 - 66	- 311 300
	lark tnto	10	ys	eM 03	in a ti	na to	sM n	ı, P	n e [s]	
	valuator Tadmui	3	v m =	י ניטיני	~ °	ء م ک	3=:] -	12 23	

Data lost or no event switch response made by evaluator.

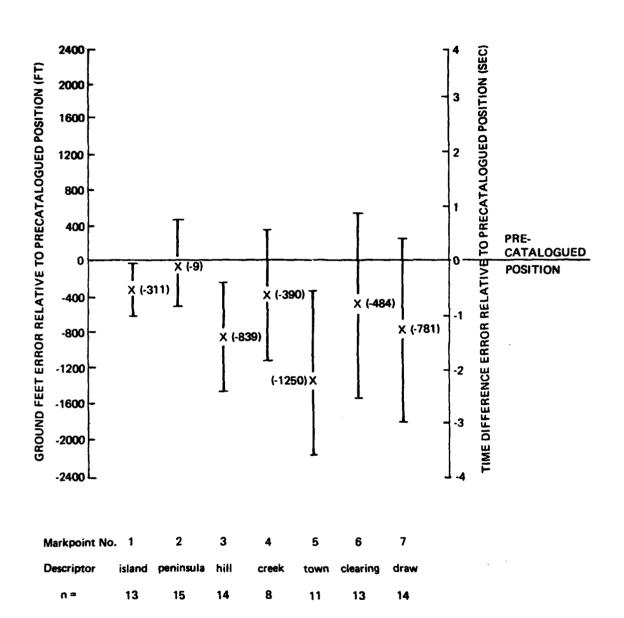


Figure B-3. Summary of Mark Point Data - Hunter-Liggett

Table B-4
Mark Point Description -- N-NAV-300, Part II

Mission: N-NAV-300 Part II Speed: 360 kts Altitude: 300 ft Mark points plotted inflight by evaluator responding to audio signal

MARK POINT NUMBER	IDENTIFIER	POINT-TO-POINT DISTANCE (nm)
1	Rich Mountain	(Start) 14.0
2	Dry Creek Mountain intermittent stream	16.4
3	Highway 80 Ridge	9.6
4	Peak 1383 ft	8.0
5	Peak near Fourche Mountain	10.5
6	Peak southeast of Round Mountain	11.9
7	Primary and secondary streams confluence	6.7
8	Ridge before tower	8.3

Table B-5
Mark Point Description -- N-P-300, Part I

Mission: N-P-300 Part I Speed: 360 kts Altitude: 300 ft Mark points plotted inflight by evaluator responding to audio signal

MARK POINT NUMBER	IDENTIFIER	POINT-TO-POINT DISTANCE (nm)
1	1400 ft peak on right	(Start) 3.9 ´
2	Transmission line crossing ridge	2.9
3	Nashoba spur	5.1
4	Highway 271 spur	4.8
5	1350 ft spur	5.5
6	Third ridge	3.5
7	Spur southeast of peak 1450 ft	4.6
8	Highway 43 hill	5.8
9	South peak	6.8
10	Perpendicular ridge	5.1

Table B-6
Mark Point Description -- SEEKVAL A

Mission: SEEKVAL A Speed: 360 kts Altitude: 500 ft Mark points plotted inflight by evaluator responding to audio signal

MARK POINT NUMBER	IDENTIFIER	POINT-TO-POINT DISTANCE (nm)
1	Bend in I-5 and railroad	(Start) 3.6
2	Tenino Road - Railroad	7.4
3	River - Powerhouse	12.1
4	Road - railroad crossover	9.3

Table B-7
Mark Point Description -- W-TA-200

Mission: W-TA-200 Speed: 480 kts Altitude: 200 ft Mark points plotted inflight by evaluator responding to audio signal

MARK POINT NUMBER	IDENTIFIER	POINT-TO-POINT DISTANCE (nm)
1	Shallow saddle	(Start) 13.3
2	Albert, third ridge	7.1
3	Big Fork Ridge at road bend	10.1
4	2443 ft peak	13.1
5	Ross Mountain	8.5
6	Saddle east of East Poteau Mountain	7.5
7	970 ft hill	6.7
8	Midland Dam	10.1
9	Railroad - road	12.2
10	Dog Creek Spur	9.5
11	Lake Wister Dam	11.4
12	River - railroad	10.2
13	Highway 259 ridge	5.3
14	Blue Bouncer Mountain	8.5
15	1100 ft hill	12.0

Table B-8
Mark Point Description -- W-NAV-400

Mission: W-NAV-400 Speed: 480 kts Altitude: 400 ft Mark points plotted inflight by evaluator responding to audio signal

MARK POINT NUMBER 1	IDENTIFIER Dual Highway 20	POINT-TO-POINT DISTANCE (nm) (Start) 5.0
2	Transmission line - Highway 79 crossing	6.9
3	Leton (town)	10.7
4	Transmission line - road east of Rocky Mountain	n 18.2
5	Road - railroad near Lumber	12.0
6	Transmission line - north of Bethel	4.9
7	Tower - hill 525 ft	12.0
8	Road - railroad northeast of Emmett	8.2
9	Railroad bend near Ozan Creek	11.7
10	500 ft hill	9.6
11	Peninsula before Daisy Bridge	10.8

Table B-9
Mark Point Description -- E-TA-200

Mission: E-TA-200 Speed: 480 kts Altitude: 200 ft
Mark points plotted inflight by evaluator responding to audio signal

MARK POINT NUMBER	IDENTIFIER	POINT-TO-POINT DISTANCE (nm)
1	Ridge past Twin Bridges	(Start) 13.7
2	Highway 70 hill	10.6
3	Gaston hill	14.3
4	Fourche Mountain	10.1
5	Parks (town)	9.9
6	Pilot Knob hill	11.1
7	810 ft hill	7.1
8	Blue Mountain Lake Dam	9.6
9	Potts Ridge	7.6
10	Hogan Mountain draw	9.0
11	1090 ft ridge	11.4
12	1660 ft spur	8.9
13	Lake Spur	- 8.8
14	Peak at cove	10.5
15	Saddle at end of film	6.3

APPENDIX C PARTICIPANT DEMOGRAPHICS SUMMARY

MITAC-II DEMONSTRATION EXERCISE

PARTICIPANT DEMOGRAPHICS

Date ____

	Rank					
			t experience (bot ft type and positio		and pr	ivate) in
			Position			
Aircraft	Type	Pilot	RIO	BN		A0
F-4 RF-4B F-14 A-4 A-6 OV-10		70-1900 850-950 400-2300	1200-2100 850 270-275	1100-170		
2. Ple	ease list al	l Navigati	on training course	s you have	received:	
Date	Course Tit	tle P	rimary Objective	Classroom Hours	Flight Hours	Low-Level Emphasis (Yes,No)
<u>B</u> a	asic Jet Nav	igation T	raining	2-50	5-35	No
<u>Lo</u>	ow-Level Nav	igation T	raining	2-25	3-18	<u>Yes</u>
<u>Lo</u>	ow-Level Tac	tics I	nstructor-Training	4-8	10-20	Yes

TARPS___

Low-Level Recce 20-39 11-20 Yes

3. Please list your low-level (terrain flight) experience. Indicate combat (C) or training (T).

Altitude: Min - 200-ft 2-200 hrs C,T 200 - 500-ft 20-400 hrs C,T

Airspeed:

the desirable of the second state of the second second second second second second second second second second

less than 360 Kts $\frac{0-2000}{0-300}$ hrs $\frac{C}{C}$, $\frac{T}{C}$ 480 Kts $\frac{0-300}{0-125}$ hrs $\frac{C}{C}$, $\frac{T}{C}$ more than 540 Kts $\frac{0-25}{0-25}$ hrs $\frac{C}{C}$, $\frac{T}{C}$

Sortie length:

4 Considering your overall low-level experience as 100%, how would you apportion that to experience with the following types of terrain:

- a) Desert 10-80
- b) Forest 5-30
- c) Mountains 1-40
- d) Hills 2-25
- e) Plains 1-20
- f) Urban areas 1-5
- g) Rural areas 3-95

5. What proportion of your low-level experience is in:

VMC daytime 70-100

VMC nighttime 1-20

IMC daytime 1-10

IMC nighttime 5-10

6. What maps are you most familiar with for

a) Mission planning? 1:250,000 and 1:500,000

b) Inflight reference? 1:250,000 and 1:500,000

- 7. Which maps do you like best for
 - a) Mission planning? 1:250,000
 - b) Inflight reference? 1:500,000
- 8. Please list other Nav-Aids, materials and/or devices which you have found to be useful for low-level navigation and flight planning (e.g., photomaps, recce photography, sensor imagery, etc.).

Photos, photomaps, sensor imagery, and INS

APPENDIX D ILLUSTRATED LECTURE QUESTIONNAIRE SUMMARY

MITAC-II DEMONSTRATION EXERCISE EVALUATIVE QUESTIONNAIRE NO. 1 (Illustrated Lecture)

	Date
Name and Rank	Duty Phone (Commercial)
usefulness of the illustrated lect fixed-wing aircraft, low-level naviga right or wrong answers, but the though significant influence on how we can	tion training. There obviously are no httfulness of your answers will have a improve our map interpretation and tions should be answered relative to
PRELECTURE	
Please rank order the importance of t meeting low-altitude navigation requir	ne cartographic features shown below in ements as you currently view them.
(1 - most important, 4 = least importa	nt)
Topography and terrain analysis Vegetation patterns Hydrography Cultural features	$ \begin{array}{c} \frac{1}{4} \\ \frac{2}{3} \end{array} $
Comments: o Ranking will vary depending on type	of terrain and mission scenario.
o Hydrography and vegetation patter changes with location and season.	ns somewhat related; their importance
o Vertical development probably best	feature available

1. Please rate the components of the illustrated lecture by filling out the matrix. For example, if you think the <u>pictorial examples</u> of <u>vegetation patterns</u> were fairly representative of what you would expect to encounter during actual flight operations, write "3" in the corresponding row and column of the matrix.

TOPOSHOW.	PATE AT ANALYSIC	HOSMS ON	CUL DORAPHY	TURES
4	4	4	4	
4	4	4	4	1
4	4	4	4	I

Perfect = 5

Adequate = 2

SOMETIMES

Good

Fair

Poor

YES

NO

Verbal Description Pictorial Examples Cartographic Examples

2. Was the verbal description for the corresponding lecture section: (Y = Yes, N = No)

a.	easily understandable?	15_	0	0
b.	too long?	1	11	3
c.	too short?	1	13	1
d.	too general?	0	14	1
e.	too detailed?	_1_	13	11
f.	too much oriented towards cartographers'	_1_	13	11
	jargon or concern?			
g.	adequately concerned with matters beneficial	_12_	1	22
	to your flight environment?			
h.	informative relative to overall navigation	<u> 15</u>	0	0
	training requirements?			

Comments:

- o Presentation very good
- o Need to discuss relationships among individual features
- o Correlation of all terrains and each aspect of a particular environment need to be emphasized
- o Need to draw all four segments together in a summary of low-altitude navigation

- 3. What, if anything, bothered you about the pictorial examples used (e.g., field of view, range to feature, representativeness of example, etc.)?
 - o Field of view too narrow
 - o Map picture should be oriented the same and contain the same ground coverage as the pictorial example
 - o Altitude and range to feature needed
- 4. What, if anything, bothered you about the cartographic examples used (e.g., map scale, shading, features portrayed, etc.)?
 - o Map overlap sometimes bothersome due to shading road portrayal, etc., differences
 - o Vegetation segment could use more emphasis
 - o Some of the general statements may be valid for some regions but not others
- 5. Prior to the lecture, you rank-ordered the importance of cartographic features for your low-altitude navigation requirements. Did that rank order change in your view based upon the illustrated lecture?

No change for majority of evaluators (Yes - 5, No - 10)

If so, please provide new rank order (1 = most important, 4 = least important)

Topography a	and terrain	analysis	
Vegetation p	atterns		
Hydrography			
Cultural fea	tures		

1_	
 4	
 2	
3	

- 6. Please describe how the illustrated lecture will influence your flight planning.
 - o Will pay more attention to topography and vegetation
 - o Will certainly aid in converting a map into a three-dimensional picture
 - o Very little. Information will backup methods already used
- 7. How do you think the illustrated lecture will affect your visual search, that is what you will look for and how you plan to find it, during actual and simulated navigation training flights?
 - o It probably will not affect the visual search
 - o Greater emphasis on topography

- 8. Do you think your navigation procedures (flight planning, visual search, frequency of orientation checkpoints, etc.) will change as a function of the following? If so, how?
 - a. Aircraft speed? Yes, choose fewer, more distinct checkpoints
 - b. Altitude? Yes, planform versus obliquely significant checkpoints
 - c. Other inflight tasks? Yes, as the tasking increases, the checkpoints must be more distinct
- 9. Any other comments that you might want us to consider for map interpretation and analysis training?
 - o A module specifically on maps (i.e., symbols used, indexes, etc.)
 - o Use of more graphics to illustrate a point
 - o Terrain analysis is quite different at 200 kts as compared to 480 kts Subtle terrain changes are not noticed
 - o Might consider actual flight planning with slides

10. The next items are in the form of an opinion questionnaire. Consideration is given to the MAP INTERPRETATION section and the CONTOUR INTERPRETATION section of the illustrated lecture. Please place a check-mark by the statement which corresponds with your opinion or write a short statement expressing your opinion.

MAP INTERPRETATION SECTION

Format		
14	()	Retain dual screen Prefer single screen Prefer split screen (small insets)
1	()	Prefer split screen (small insets) Other:
Narrat 12	()	Retain present nace
	()	Increase pace
1 2	()	Increase pace Decrease pace Other: Some areas need a slower pace, others faster
Narrat		
15		Audio Quality Adequate
	()	Audio Quality Inadequate Other:
Conter	nt-So	cope
9	()	Retain present scope Expand scope Reduce scope
O	} }	Reduce scope
	()	Other: Include JOG AIR discussion and final lecture on tactics; add airfields
Conte	nt -	Level of Detail
13	()	Retain present detail
2	()	Retain present detail Increase detail Reduce detail
	} }	Other:
		Map Examples
4	()	Retain present examples
11	}	Improve examples Reduce examples Other: Use same map edition; more varied terrain; displayed area
	()	Other: Use same map edition; more varied terrain; displayed area on map and slide to coincide
C	_ &	
	1t -	Terrain Type Examples (Pictorial) Retain present examples
9 6	()	Retain present examples Expand examples Reduce examples Other: Need more varied terrain; improve some faded photos
	()	Reduce examples
	()	other: Need more varied terrain; improve some raded photos

CONTOUR INTERPRETATION SECTION

Format		
14 ()	Retain dual screen Prefer single screen Prefer split screen (small insets) Other:
()	Prefer single screen
1 ()	Prefer split screen (small insets)
()	Other:
M + d -		
Narratio	'n	Detain numerat need
13	{	The marks and a second
2 }	<	Documents have
·	{	Retain present pace Increase pace Decrease pace Other:
•	,	outer.
Narratio	n	
15 ()	Audio Quality Adequate
ĺ	j	Audio Quality Adequate Audio Quality Inadequate Other:
()	Other:
Content	-	Scope
14 ()	Retain present scope Expand scope Reduce scope
1 ()	Expand scope
(- {	Reduce scope
()	Other:
Content	_	Level of Detail
14 /	٦	Retain present detail
- ` }	ί.	Increase detail
1 }	{	Reduce detail
- }	5	Retain present detail Increase detail Reduce detail Other:
Content	-	Map Examples
11 ()	Retain present examples
3 (Į	Improve examples
. }	(Retain present examples Improve examples Reduce examples Other: Enlarge examples
1 ()	Uther: Enlarge examples
Content	_	Terrain Type Examples (Pictorial)
		Retain present examples
3 (Í	Expand examples
ì	Í	Reduce examples
(Ś	Other: Need larger field of view; more varied terrain types
_		
	-	Graphics Examples
7 ()	Retain present examples
5 (Į	Improve present examples
1 }	₹	Reduce examples
(J	Other: Need more varied terrain types
Content	_	Relevance of Examples
10 ()	Retain present examples
2 (ĺ	Improve present examples
3 ()	Other: Correlate the areas and combine features

APPENDIX E SIMULATOR EXERCISES QUESTIONNAIRE SUMMARY

MITAC-II DEMONSTRATION EXERCISE EVALUATIVE QUESTIONNAIRE NO. 2 (Simulator Exercises)

	Date	
Name	and RankDuty Phone (Commercial)	
1.	Were the materials provided for flight planning sufficient for meet inflight task requirements? Yes - 11, No - 3	ing
	If not, what is needed?	
	o Charts in some cases were too cumbersome o Ability to plot headings on map - need variation o Dividers, compass rose	
2.	Did you have sufficient time to prepare for each fight? Yes - 15, No - 0	
3.	Did your approach to flight planning change as we went from "al track" to "corridor" maps? If so, how? Yes - 13, No - 1	ong
	o Time hacks less important and more general o Had to be aware of much larger area o Used topographical features more and cultural features less	
4.	Did the two different corridor widths have a differential effect your flight planning? If so, how? Yes - 3, No - 12	on
	o Had to review more area O Altitude more critical as pertaining to field of view	

6. How do you rate the following aspects of the simulation flights: (Please circle one number per item) (Circled answers represent the highest frequency response by the evaluators.)

	Excellent	<u>.</u>			Poor
Visual Scene (Films) Active Cockpit Displays	⑤	4	3	2	1
Cockpit Lighting	5	4	3	2	i
Event Switch Throttle Control	5 5	4)	3 3	2 2	1
Screen Brightness Image Sharpness	5 5	(4)	3 3	2 2	1

6. How useful were the following for maintaining geographic orientation?
(Circled answers represent the highest frquency response by the evaluators.)

	Extremely Useful				Not <u>Useful</u>
RMI	5	4	3	②	1
Airspeed Indicator	5	4	3	②	1
Clock	5	4	3	2	1
Detailed Track Plots	5	4	3	2	1
Four-mile Corridor Plots	5	4	3	2	1
Ten-Mile Corridor Plots	5	4	3	2	1
Topographic Features	5	4	3	2	1
Vegetation Patterns	5	4	3	2	1
Hydrographic Features	5	4	3	. 2	1
Cultural Features	5	4	3	2	1

- 7. Did you experience any differences in your ability to maintain geographic orientation as the flight speed increased between sets of flights?
 Yes 8, No 7
 - o Specific features were difficult to see, hard to find some markpoints
 - o Higher speeds more comfortable
 - o Made no difference

- 8. Were the debriefing runs on the simulator helpful for gaining a better understanding of map interpretation and terrain analysis? Yes -15, No -0
 - o Especially with the light pointer
 - o Allowed one more chance to view terrain and reinforce patterns or correct misconceptions. Use same speed on debrief as on performance run
- 9. Were the checkpoints and "mark points" similar to those you would use in operational situations"
 - a) Before these exercises? Yes - 1, No - 11, Maybe - 1
 - o At high speeds, only very significant features are used as checkpoints
 - b) As a result of these exercises? Yes - 0, No - 9, Maybe - 4
 - o It will not change planning, but will increase awareness and knowledge of such features
- 10. Considering training objectives, how beneficial do you think the extremely wide field-of-view of the Boeing simulator is for acquiring navigation skills?
 - o Wide screen allowed very accurate presentation of actual low-level navigation very valuable
 - o Great except for blurring on periphery
 - o Extremely useful

11.	For the items listed below, please check or write in your recommendation or opinion.		
Along-Track Performance Exercises			
10 3 2	 () Retain present format and number of exercises () Expand number of exercises () Reduce number of exercises () Other: <u>Increase variety of terrain; maybe change order of films</u> 		
Along	-Track Debrief Exercises (Simulator)		
8 1 1 1	 () Retain present format () Improve narrative content () Improve narrative cueing () Improve narrative content and cueing () Delete simulator debrief () Other: Debrief at airspeed flown; use the light arrow 		
Limit	ed-Corridor Performance Exercises		
12 1 2	 () Retain present format and number of exercises () Expand number of exercises () Reduce number of exercises () Other: Expand corridor width to 5 - 10nm; increase variety of terrain 		
Limit	ced-Corridor Debrief Exercises (Simulator)		
9 1 1 4	 () Retain present format () Improve narrative content () Improve narrative cueing () Improve narrative content and cueing () Delete simulator debrief () Other: Debrief at same speed as performance run; use light arrow 		
Corr	idor Performance Exercises		
11 2 1 1	 () Retain present format and number of exercises () Expand number of exercises () Reduce number of exercises () Other: W-NAV-400 could be omitted or reduced in length 		

COFFIC	gor	νe	brief Exercises
7 2 2 4)))	Retain present format Improve narrative content Improve narrative cueing Improve narrative content and cueing Delete simulator debrief Other: Debrief at performance speed; use light arrow
Pre-F	ligh	ıt-	Mission Planning Materials were:
12	()	Satisfactory Unsatisfactory (Specify): Order - Precise low-altitude navigation key Other: Consider not using laminated charts; preflight tape needs to walk through mission rather than discussing each individual major topic
Post-	Fli	ght	:-Debrief Materials were:
15	{))	Satisfactory Unsatisfactory (Specify): Other:
Audio	Cue	eir	ng of Mark Points was:
14	()))	Satisfactory Unsatisfactory (Specify): Other: Some were slightly off
Refer	enc	es	to Feature Positions were:
12 3			Satisfactory Unsatisfactory (Specify): Other: Difficult to see certain features such as multiple ridges, spurs, and draws. A visual reference on film would be helpful.
Posit	ion	Re	eference Should be Provided:
4 6 5	(E-W/N-S Left-Right/Up-Down Other: Clock codes; distance; left or right of track; light pointer

The t	total	number of exercises for Initial Terrain Flight Training is:
10 4 1	()	Satisfactory Should be increased Should be decreased Other: Perhaps one "lost" exercise; desert operations; reduce distractors initially, then add on more later
The v	variet	y of Terrain for Initial Terrain Flight Training is:
6	()	Satisfactory Should be increased Should be decreased Other: Desert, high mountains; jungle, snow could be added
O	} {	Should be increased
2	} }	Other: Desert, high mountains; jungle, snow could be added
Empha	asis s	hould be on:
13	()	Performance feedback Performance evaluation Other
1	()	Performance evaluation
1	()	Other
	0	Leave evaluation to 101/102 etc.
	0	Increasing our recognition ability - map interpretation, reading the JOGs properly and relating to the actual terrain. $\underline{\text{JOG AIR}}$ emphasis vice $\underline{\text{TPC}}$ maps.
	0	Both feedback and evaluation.

Where does this program fit in USMC Training?

- 5 () Training Command 5 () Replacement Air Group 3 () Unit Level
- O A good start point would be to introduce this at the training command level to give them a better understanding of map interpretation.
- Need to get some flight time and experience under your belt first.
- Course needs to be precisely defined. It is currently designed as Map Interpretation and Terrain Analysis Course. It performs this objective beautifully. It is not a <u>navigation</u> training course. It does not talk about tactics nor are the checkpoints those which would normally be used. This should be emphasized. Generally the course was excellent. It demonstrates a very definite requirement to be able to determine position using topography primarily at a minimum. Would like to see entire slide program and at least a 16mm capability of some sort hit the fleet.
- Also reviewed in unit level. Enjoyed the program. My learning curve was remarkable (for me!). The program as is teaches map interpretation and terrain analysis better than any method I can think of, it does not however teach navigation in high-speed low-altitude flight and it must be carefully differentiated. It nevertheless is extremely valuable. The cockpit simulation was good, however the instrumentation (excepting the clock) is needless because there is no task associated with them. Improvements needed: better film quality, varying terrain, and refinement of lecture material.

Additionally, the entire program should be reviewed to purge any contradictory statements with good <u>navigational</u> techniques (e.g., program states that a tower is not a good feature to confirm your position because of numerous unmapped towers. True enough! But wrong if you consider flying a course (HdG) for 3 minutes at a given airspeed and at 3 minutes you should be over a tower, then you've got a good confirmation of position!)

Program also needs a segment at the end of the lecture which ties together topography, vegetation, hydrography, and cultural features. The lectures treat them separately which is fine, but you need to pull them all together to show their interaction and play!

I feel that a definite division has to be made between high-speed low-level map interpretation and terrain analysis and high-speed low-altitude navigation.

- o The slide/sound presentations are very adaptable to training command and unit level.
- o Fly debrief before mission without designation mark points.
- Also unit level. Periphery of film imagery blurred need better resolution. Need to add throttle control to adjust a/s to the minimum available (within safe limits of projector) for instructional purposes. Also, it allows the student to readjust his a/s to get back on track time-wise. Differences of map and film must be brought out prior to run, (e.g., tell us if a major highway was not built when film was shot even though it shows on the map). Need to expand course material to cover in more detail how to reorient yourself if you got off track.
- o Also unit level. Cockpit light on acetate is a problem. Maps should contain color tint/declination and other marginal information.
- o Also RAG
- Training is universally common to various USN missions at training command level (i.e., attack, recce, photo escort). Trainees can all be trained in detailed chart analysis at a single point. At RAG level, specific mission tasks should receive higher concentration with chart analysis being understood.

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